

### AUCKLAND BONE AND JOINT SURGERY

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# ARTHROSCOPIC SUBACROMIAL DECOMPRESSION AND ACROMIOPLASTY REHABILITATION PROTOCOL

## Phase 1:

Begins immediately after surgery to approximately 4 weeks post-op

- 1. Sling for everyone: wear for comfort for 2 weeks post-op; discontinue sling at 2-4 weeks
- 2. Cryotherapy as needed for pain relief (cryocuff or ice pack)
- 3. Passive to active shoulder ROM as tolerated ROM goals:

Forward flexion: 140°

ER at side: 40°

IR: behind back with gentle posterior capsule stretching

NO abduction or 90/90 ER until 4-8 weeks post-op

- 4. Grip strengthening
- 5. Pulleys/canes to assist shoulder ROM
- 6. NO resisted shoulder ROM
- 7. Active wrist/passive elbow ROM exercises
- 8. Day 10-14 suture removal
- 9. Aquatic/pool therapy (2-4 weeks post-op)

Shoulders totally submerged

Slow active motion within precautionary ROM with emphasis on good biomechanics

#### Phase 2:

From 4-8 weeks post-op

- 1. No sling
- 2. Increase shoulder ROM as tolerated ROM goals:

Forward flexion: 160°

ER at side: 60°

IR: behind back and at 90° of abduction with gentle posterior capsule stretching

- 3. Begin light rotator cuff and deltoid isometric exercises with arm at side advance to therabands as tolerated
- 4. Passive ROM stretches at end range to maintain flexibility
- 5. Aquatic/pool therapy continue same exercises as in phase 1 without ROM limitations increase speed of movement as tolerated

# Phase 3:

From 8-12 weeks post-op

- 1. Progress to full shoulder ROM without discomfort
- 2. Advance strengthening as tolerated
- 3. Begin eccentrically resisted motions and closed chain activities
- 4. Add gym machines as appropriate 10-12 weeks post-op (chest press, rowing, latissimus pull-downs, triceps, biceps)

#### Phase 4:

From 12-16 weeks post-op

- 1. Functional progression for sports and activity-specific tasks (i.e. golf, tennis, rugby)
- 2. Interval sport programs as indicated
- 3. Advanced strengthening as indicated

ROM = range of motion AROM = active range of motion IR = internal rotation PROM = passive range of motion AAROM = active assisted range of motion ER = external rotation

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